

# Constellations Operations : Challenges...and ambitions !

30 & 31 Mars 2023 CNES COMET « Opérations du futur »

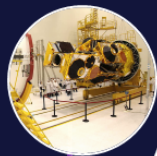
Sébastien PIRO



# (MEGA) Constellation operations challenges at a glance...



Lessons Learned  iridium



1<sup>st</sup> LEOP  
AUTO Sequence



Save  
Time

Design  
Robustness

Multiple critical  
contingencies  
recovered successfully

Constellations  
Operations

Reduce  
OPEX

Flexibility



Innovative Operational  
Concepts



Multi Skilled People

**NOT ACHIEVABLE** with “standard” processes !

# (MEGA) Constellation operations challenges

**OPEX** : MORE WORKLOAD, MORE PEOPLE, MORE GROUND STATIONS...

## Constellation Deployment = "Space Marathon"

- Challenging schedule needs flex & trained people !
- Don't forget to manage the birds "already flying"!
- **Potential CONTINGENCIES**

## Ground Resources Management

- Potential lack of accessibility
- **Overlap operations = "BOTTLENECK EFFECT"**
- Adding more Ground Stations will not solve potential **TM/TC interferences !**

## MAINTENANCE COSTS : Certifications, tools & TURNOVER !

- **Personnel to train /to hire**
- **Maintain competencies**
- Ground/board Tools to be maintained



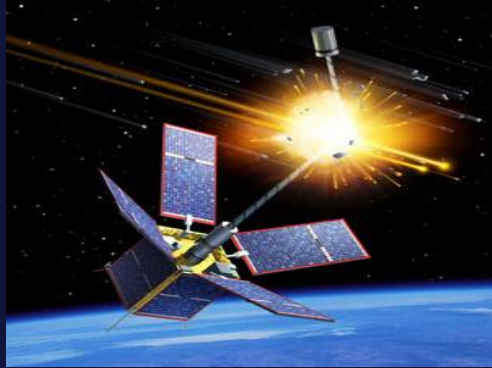
**PRICEY & TIME  
CONSUMING !**



# (MEGA) Constellation operations challenges

## SAFETY & SECURITY

- > Prevent **COLLISION** in orbit !
  - LEO Orbit congested
- > Prevent **CYBER attacks** !
  - Less HW, More SW

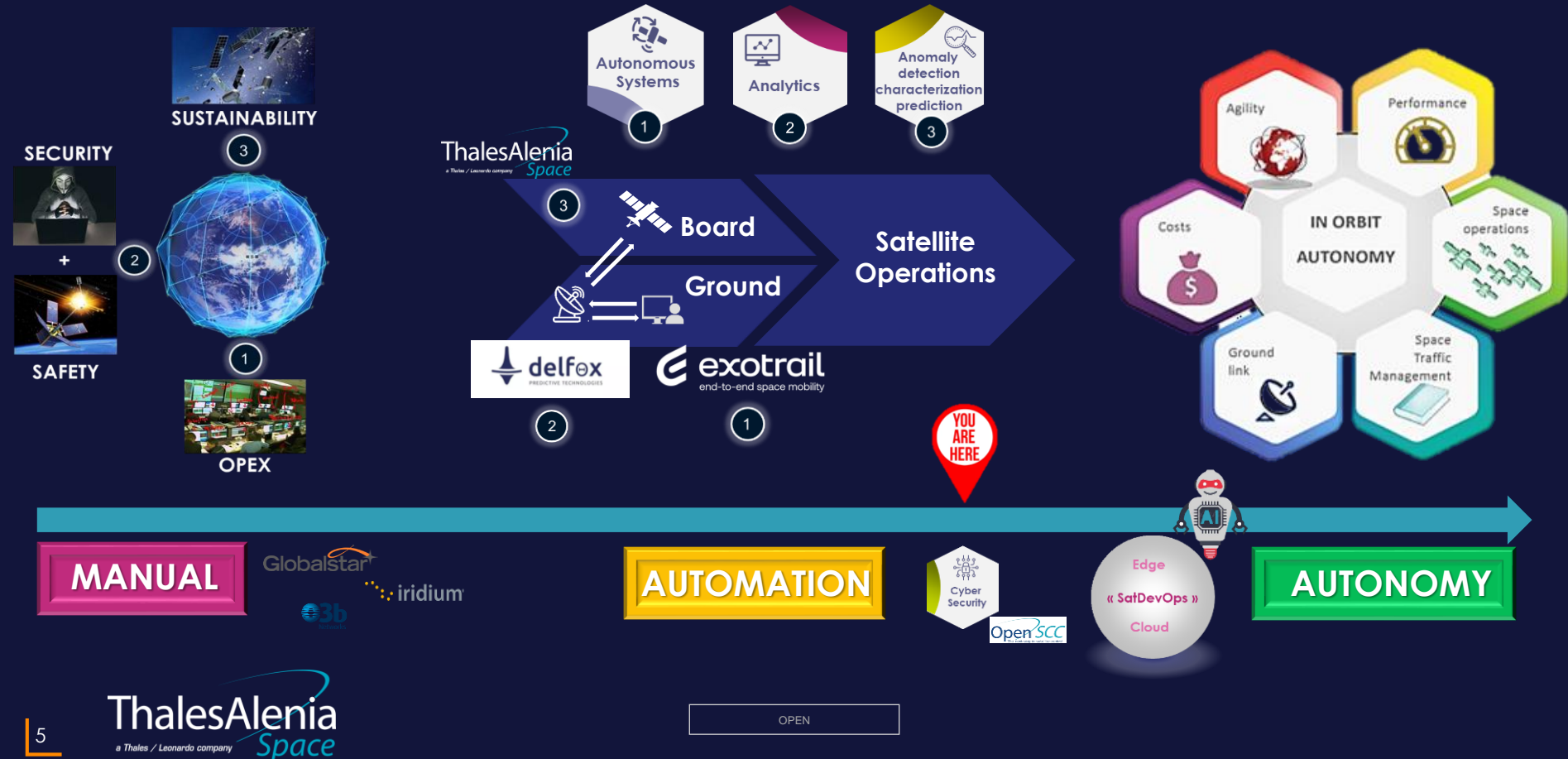


## SUSTAINABILITY

- > « **PREVENT before to ACT** »
  - Best way to reduce workload !
- > **Protect Earth and Space....and SPACE BUSINESS !**
  - **Responsible OPS behavior** to reduce environmental impact
  - **LOS, SSR** (Space **S**ustainability **R**ating)

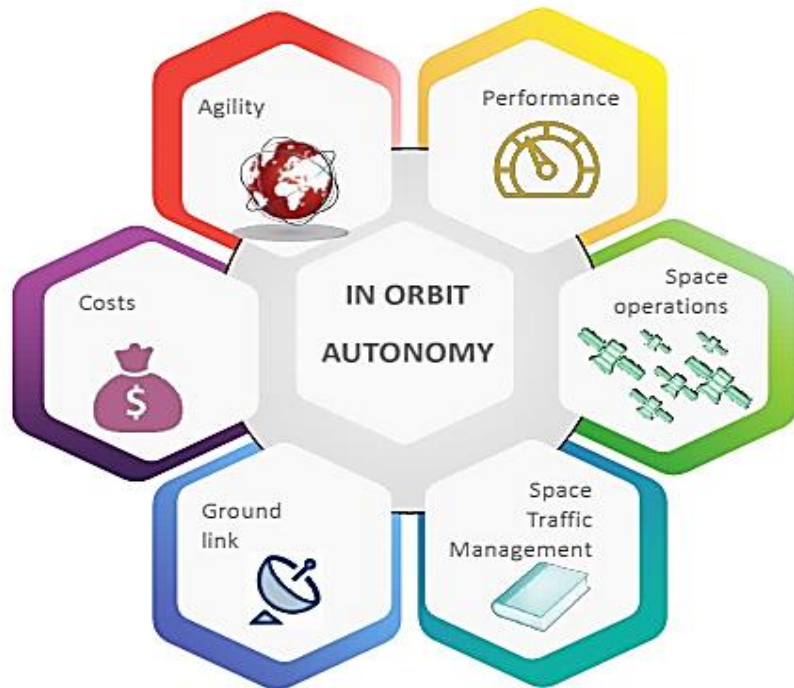


# Constellations Operations Tomorrow ...





# What impel us to work on in-orbit autonomy ?



A CNES-TAS COMMON SHARED VISION !

## 01 – AGILITY

Satellites and Missions become more complex.

## 02 – PERFORMANCE

To reach a **NEW LEVEL** of performance (ground/board operational loop reduced)=

## 03 – SPACE OPERATIONS

More Satellites makes **GROUND** management more difficult.

## 04 – SPACE TRAFFIC MANAGEMENT

**SAFETY** needs to be **guaranteed** while respecting shared rules in a efficient way

## 05 – GROUND LINK

Ground is expensive...ground stations network is already at a **CRITICAL** point for constellations

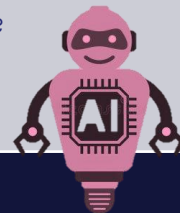
## 06 – COSTS

**Constellations Space Programs COSTS** are now requiring a high level of autonomy !

# Level of autonomy for satellites operations : Where we are ?

Yesterday  
Today  
Tomorrow ?

Level of automation	On GROUND	On BOARD
<b>LOW</b> – Satellite or Fleet of satellites	<ul style="list-style-type: none"> <li>- Operational procedures scheduled for each satellite on each phase</li> <li>- Permanent presence of Controllers &amp; Experts</li> </ul>	<ul style="list-style-type: none"> <li>- Very <b>LOW on-board autonomy</b>,</li> <li>- Mainly automatisms for <b>satellite SAFETY</b></li> </ul>
<b>MEDIUM</b> – LARGE constellation (<100)	<ul style="list-style-type: none"> <li>- ROUTINE operations scheduled (AUTOMATION)</li> <li>- Controllers 24/7/365. Experts in “office hours”</li> <li>- Additional Controllers &amp; Experts on call</li> </ul>	<ul style="list-style-type: none"> <li>- <b>More automation</b> onboard (Event Action, Action Sequences, LEOP Auto Sequence, etc)</li> <li>- Execution of <b>Onboard Control Procedures</b></li> </ul>
<b>HIGH</b> – MEGA constellation (>=100)	<ul style="list-style-type: none"> <li>- Automate ALL phases ?</li> <li>- <b>A Multi-tasks Operator</b> ?</li> <li>- A “<b>virtual assistance</b>” (AI) mode “<b>ON DEMAND</b>” ?</li> <li>- <b>Rely on CLOUD</b> for additional Ground resources “<b>ON DEMAND</b>” ? (SW, HW, AWS GS, etc)</li> </ul>	<p><b>Toward A “SMART” AUTONOMY ?</b></p> <ul style="list-style-type: none"> <li>- <b>AUTO</b> Maneuvers/collision avoidance ?</li> <li>- <b>High Computing capacities</b> + <b>Edge/Cloud env</b> + <b>AI/ML</b> to improve operations,</li> <li>- Anomalies prediction with <b>AI</b> ?</li> <li>- <b>Autonomous Analysis</b> to ease decision making process ?</li> <li>- <b>Automate onboard recoveries</b> ?</li> </ul>



# Collision Avoidance Solutions TODAY : “state of the art” at a glance

## « DIY »

CSM: conjunction summary message  
Envoyé 72h avant le TCA (time closest approach)  
Miss distance 1km  
Vitesse, dispersion, caractéristiques des orbites

SpaceTrack (JSPOC)

Satellite owner/operator

O/O sat ephemeris (daily basis)

- Entretien d'une bdd de TLE publique et gratuite
- Entretien d'une bdd d'ephemeris (données opérateurs) (catalogue SP)
- > partagée avec les agences spatiales
- Calcul des probabilités de collision toutes les 8h sur 7 jours et envoi de CSM/CDM (précision à 100m)
- Quand un opérateur propose une manœuvre, retour dans les 8h

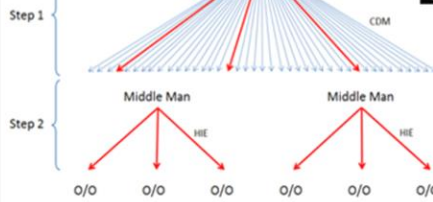
- Evaluation du niveau de risque de collision selon ses propres critères
- Dédution des HIE « high interest event » (5% du temps)
- Décide de faire ou non la manœuvre
- Calcul de la manœuvre, proposition au JSPOC pour check et implémentation si retour positif

## « Middle Man »

LEO LABS



share my space



### COLA OPERATIONS – Automation & AI/ML

- Given enough input data, a Machine Learning (ML) algorithm can be trained to reproduce similar outputs as a human
- Training data: CDMs and other ancillary info along with the decision made
- Additional training data can be obtained by means of simulation (digital twin)
- Decision parameters and different decisions to be identified and deeply analysed
- Each operator could train the system based on its own needs, interest and experience with its own data

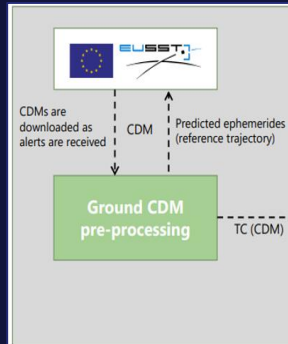
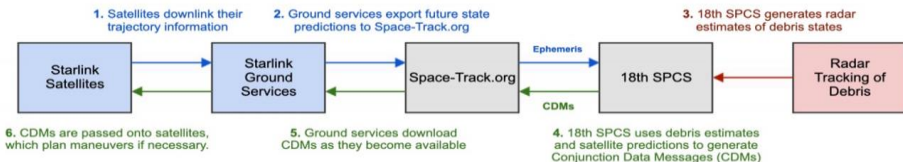


## « ADVANCED AUTONOMY »

### Collision Avoidance: Starlink-on-Debris



- Space is populated with existing debris, tracked by the 18<sup>th</sup> Space Control Squadron.
- Starlink utilizes an automated collision avoidance system, ingesting data from the 18<sup>th</sup>
  - Satellites can autonomously evaluate risk and plan avoidance maneuvers, without human input
  - Humans are still present in an oversight role, as an added measure of safety



### Ground system

- update CDM with current knowledge of satellite navigation
- filter CDM that are deemed to represent no risk



### Onboard



### Satellite system





# ANOMALY PREDICTION : Toward a « Smart » FDIR ?

2023

TAS Operation



2025

Concept “SMARTOPS”  
& Ground Segments



2030

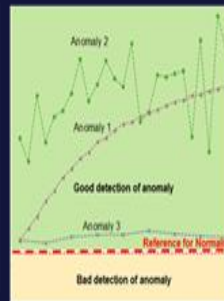
“SMART” On board  
FDIR



Satellite TM



AI Detection



20XX

Satellite Autonomy

Prediction



AI  
auto-learning

# Constellations OPERATIONS Tomorrow : TAKE AWAY !

■ CAPEX & OPEX reduction...while maintaining SAFETY & SECURITY ???

> “HOT TOPIC ” for constellations !

■ Increase AUTONOMY... & FLEXIBILITY !!

■ Still some issues and technological gaps to address :

- Computing capacities onboard are still limited...but “**Space Edge Computing**” could be an answer !
- **Create a transparent Cloud environment between GROUND and BOARD**
- Genericity vs Mission Specificities ???
- Contingencies ?? Ground « Backup Solution » needed if onboard system FAILED....





---

THANK YOU !

## Suite logicielle intégrée, orientée constellation

**spacetower™**

Simplifier l'intégration systèmes tiers (GSaaS, SSA)

Améliorer la productivité / se concentrer sur les tâches à valeur ajoutée (mission)

Changer de stratégie d'acquisition des solutions (CAPEX vs OPEX)

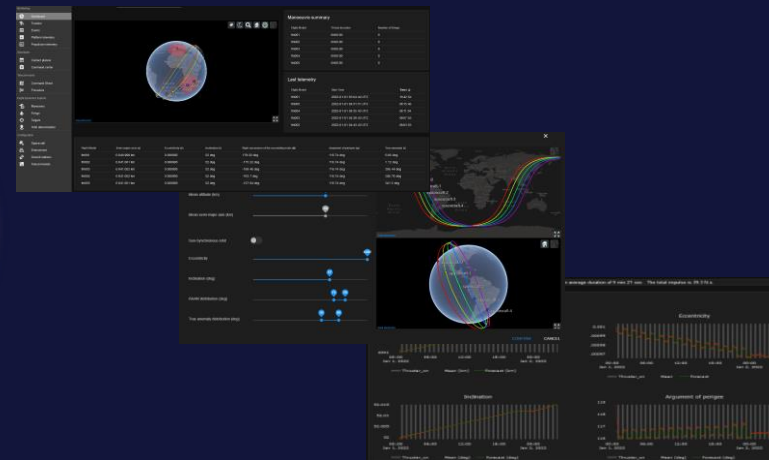
Augmenter la taille de la constellation, pas le nombre d'opérateurs au sol



Contrôler

Préparer

Exécuter



FDS intégré

Nativement Cloud

Approche Produit  
(SaaS)

Modularité (API)



**AUTOMATISATION, OPTIMISATION**





## DEL.F.SCA : COLLABORATION THALES ALENIA SPACE AUTONOMOUS SATELLITE COLLISION AVOIDANCE



DEL.F.O.X



Définition d'un environnement de simulation (maintien à poste)  
Génération des orbites secondaires  
Obtention des scénarios de collisions



Stratégie d'évitement des collisions  
Deep reinforcement learning pour les actions de mitigation



Estimation du risque de collision  
Probe sensing : probabilité d'évitement fourni par l'agent entraîné

Déroulé de scénarios d'évitements avec prédiction du risque de collision

